#pin 3 for motors(x,y)

#pin 5 for motors(z,w)

Void forward ( )

{

digitalWrite(x,HIGH);

digitalWrite(y,LOW);

digitalWrite(z,HIGH);

digitalWrite(w,LOW);

analogWrite(3,255);

analogWrite(5,255);

}

Void right ( )

{

digitalWrite(x,HIGH);

digitalWrite(y,LOW);

digitalWrite(z,HIGH);

digitalWrite(w,LOW);

analogWrite(3,255);

analogWrite(5,0);

}

Void left ( )

{

digitalWrite(x,HIGH);

digitalWrite(y,LOW);

digitalWrite(z,HIGH);

digitalWrite(w,LOW);

analogWrite(3,0);

analogWrite(5,255);

}

Void backward ( )

{

digitalWrite(x,LOW);

digitalWrite(y,HIGH);

digitalWrite(z,LOW);

digitalWrite(w,HIGH);

analogWrite(3,255);

analogWrite(5,255);

}